

Computational Complexity of Topological Logics

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- A well-known fact:

Suppose r_1 and r_2 are subsets of a topological space with r_1 included in r_2 and r_2 included in the closure of r_1 . If r_1 connected, then so is r_2 .

- We might write this in symbols as follows

$$c(r_1) \wedge r_1 \subseteq r_2 \wedge r_2 \subseteq r_1^- \rightarrow c(r_2).$$

- Once we are working in a formal language, the following issue become salient:
 - decidability and complexity
 - expressive power
 - axiomatizability
 - model theory.

- A **topological language** is a formal language with (object) variables $\mathbf{R} = \{r_1, r_2, \dots\}$, whose non-logical signature is given a fixed ‘topological’ interpretation (e.g. $\mathbf{0}$, $-$, c , \subseteq , \dots).
- A **topological frame** is a pair $\mathfrak{F} = (T, W)$, where T is a topological space and $W \subseteq 2^T$. A **topological interpretation** is a pair $\mathfrak{A} = (\mathfrak{F}, \cdot^{\mathfrak{A}})$, where $\mathfrak{F} = (T, W)$ is a topological frame and $\cdot^{\mathfrak{A}}$ a function $\mathbf{R} \rightarrow W$.
- The notions of **truth** in an interpretation and **satisfiability** (dually: **validity**) over a frame (or class of frames) are understood as expected \dots
- If \mathcal{K} is a class of frames, we denote the **satisfiability problem** for \mathcal{L} -formulas over a class of frames \mathcal{K} by $\mathit{Sat}(\mathcal{L}, \mathcal{K})$.

- The most basic class of frames to consider is:

$$\text{ALL} = \{(T, 2^T) \mid T \text{ a topological space}\}.$$

Are there any others we should look at?

- Recall that a **regular closed** set is one that is equal to the closure of its interior: $u = u^{\circ-}$.
- The regular closed sets of any topological space T form a Boolean algebra:

$$u + v = u \cup v, \quad u \cdot v = (u \cap v)^{\circ-}, \quad -u = (T \setminus u)^-$$

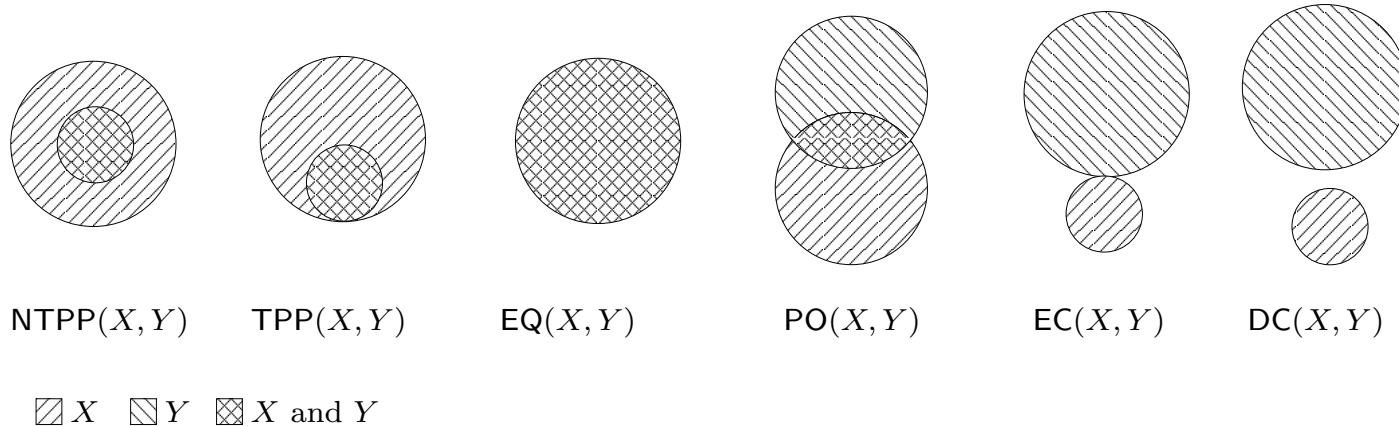
We denote the set of regular closed subsets of T by $\mathbf{RC}(T)$.

- We shall be interested in the frame class

$$\text{REGC} = \{(T, \mathbf{RC}(T)) \mid T \text{ a topological space}\}.$$

and some of its sub-classes.

- Perhaps the most intensively studied topological language is $\mathcal{RCC-8}$ (Randall, Cui, Cohn, 1992; Egenhoffer 1991):



- Example of a formula valid over REGC:

$$\begin{aligned}
 & (\text{TPP}(r_1, r_2) \wedge \text{NTPP}(r_1, r_3)) \rightarrow \\
 & (\text{PO}(r_2, r_3) \vee \text{TPP}(r_2, r_3) \vee \text{NTPP}(r_2, r_3))
 \end{aligned}$$

- The problem $\text{Sat}(\mathcal{RCC-8}, \text{REGC})$ is **NPTIME-complete** (Renz, 1998); the satisfiability problem for conjunctions of $\mathcal{RCC-8}$ -literals is **NLOGSPACE-complete** (Griffiths, 2007).

- The language \mathcal{C} (Wolter and Zakharyashev, 2000) adds Boolean operators to this language, i.e. we have the primitives $\mathbf{0}$, $\mathbf{1}$, $+$, \cdot , $-$ (with the obvious interpretations), in addition to the \mathcal{RCC} -8-predicates.

- The following \mathcal{C} -formula is valid over REGC:

$$\text{EC}(r_1 + r_2, r_3) \leftrightarrow (\text{EC}(r_1, r_3) \vee \text{EC}(r_2, r_3))$$

- The problem $\text{Sat}(\mathcal{C}, \text{REGC})$ is still NPTIME-complete.
- Using the function symbols $+$, \cdot and $-$, we can replace the \mathcal{RCC} -8-predicates with the single binary relation of **contact**:

$$C(r_1, r_2) \text{ iff } r_1 \cap r_2 = \emptyset.$$

For instance, the literal $\text{EC}(\tau_1, \tau_2)$ can be expressed as

$$C(\tau_1, \tau_2) \wedge \tau_1 \cdot \tau_2 = \mathbf{0}.$$

- A more familiar example: let $\mathcal{S}4_u$ be the topological language with primitives
 - $\mathbf{0}, \mathbf{1}$
 - $\bar{}, \circ$ (topological interior)
 - $\cup, \cap, -$ (complement in whole space).

- The following $\mathcal{S}4_u$ -formula is valid over the class ALL.

$$r_1 \cap r_2^\circ = \mathbf{0} \rightarrow r_1^- \cap r_2^\circ = \mathbf{0}$$

- We may write it in the syntax of modal logic, under the topological semantics of McKinsey and Tarski (1944):

$$\mathcal{U} \neg (p_1 \wedge \Box p_2) \rightarrow \mathcal{U} \neg (\Diamond p_1 \wedge \Box p_2).$$

- The satisfiability problem for this logic is known to be **PSPACE-complete** (Ladner, 1977).

- None of the languages in the previous summary features the *convexity* predicate c .
- Define the languages $\mathcal{RCC-8c}$, \mathcal{Cc} and $\mathcal{S4}_uc$ by adding c to $\mathcal{RCC-8}$, \mathcal{C} and $\mathcal{S4}_u$, respectively.

- The following \mathcal{Cc} -formula is valid over REGC:

$$c(r_1) \wedge c(r_2) \wedge C(r_1, r_2) \rightarrow c(r_1 + r_2).$$

- The following $\mathcal{S4}_uc$ -formula is valid over ALL:

$$c(r_1) \wedge r_1 \subseteq r_2 \wedge r_2 \subseteq r_1^- \rightarrow c(r_2).$$

- More ambitiously, we can add the predicates

- $c^{\leq k}$ (has at most k components)

- $c^{\geq k}$ (has at least k components)

for all $k \geq 0$.

- This gives us the languages $\mathcal{RCC-8cc}$, \mathcal{Ccc} and $\mathcal{S4}_u\mathcal{cc}$.

- The following \mathcal{Ccc} -formula is valid over REGC:

$$(c^{\leq k}(r_1) \wedge c^{\leq \ell}(r_2) \wedge C(r_1, r_2)) \rightarrow c^{\leq \ell+k-1}(r_1 + r_2).$$

- What can we say about the complexity of the satisfiability problems for these languages?

- The language $\mathcal{C}c$ exhibits some interesting behaviour: let $\mathcal{C}c^1$ be the restriction of $\mathcal{C}c$ to formulas containing at most one **one occurrence of c** .
- Given the variables r_n, \dots, r_1 , we can number the various terms $\pm r_n \cdot \dots \cdot \pm r_1$ as

$$\tau_0 \cdot \dots \cdot \tau_{2^n - 1}.$$

We may assume that, in the term τ_j ($0 \leq j < 2^n$), the i th factor (i.e. r_1 or $-r_i$) specifies the i th bit of j .

- We can write a $\mathcal{C}c$ -formula enforcing the condition

$$\neg C(\tau_i, \tau_j) \quad \text{for all } 0 \leq i < j < 2^n \text{ with } j - i > 1.$$

with the size of this formula polynomial in n .

- Thus, the $\mathcal{C}c^1$ -formula

$$\left(\bigwedge_{j-i>1} \neg C(\tau_i, \tau_j) \right) \wedge \tau_0 \neq \mathbf{0} \wedge \tau_{2^n-1} \neq \mathbf{0} \wedge c(\mathbf{1})$$

forces an exponentially long ‘chain’, e.g.:



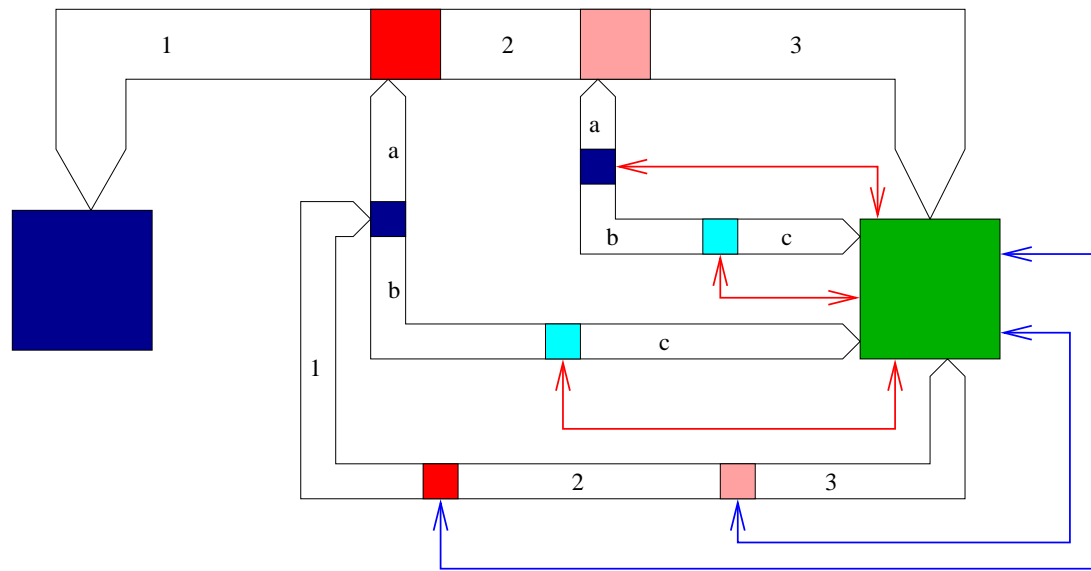
- This allows us to encode computations of any polynomial-space-bounded Turing machine.
- As a result, we have:

$\mathcal{S}at(\mathcal{C}c^1, \text{REGC})$ is PSPACE-hard.

- A matching upper bound is available:

$\mathcal{S}at(\mathcal{S}4_u c^1, \text{REGC})$ is in PSPACE.

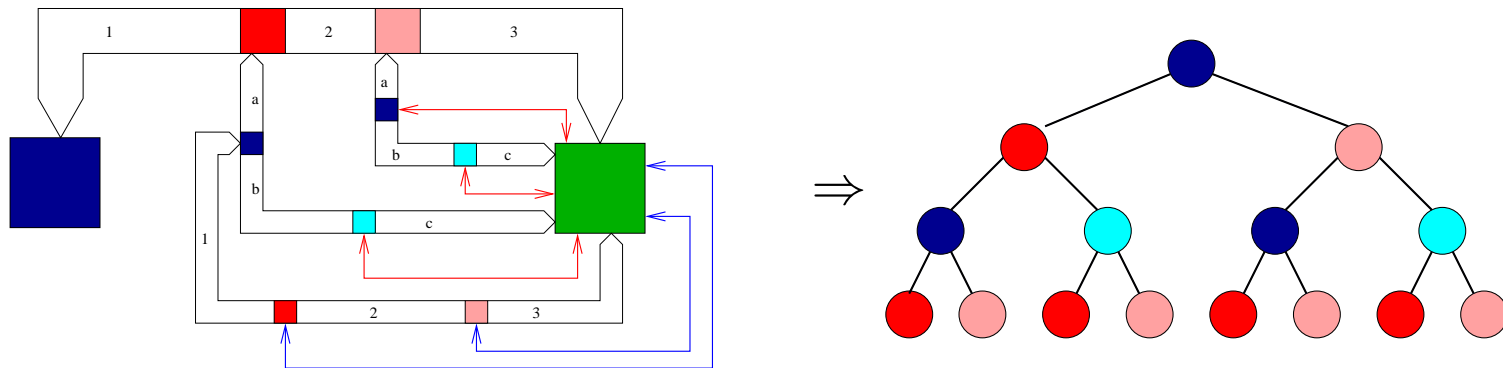
- What happens if we are allowed the full power of Cc ?
- With just two occurrences of c , we can ‘enforce’ the following configuration:



$c(\text{Blue} + 1 + \text{Dark red} + 2 + \text{Light red} + 3 + \text{Green})$

$c(\text{Red} + a + \text{Dark blue} + b + \text{Light blue} + c + \text{Green})$

- This structure can be viewed as a tree:



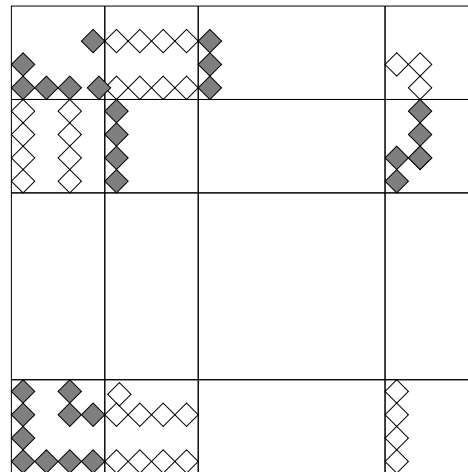
- This allows us to encode computations of any polynomial-space-bounded alternating Turing machine.
- As a result, we have:

$Sat(\mathcal{C}c, REGC)$ is EXPTIME-hard

- A matching upper bound is available:

$Sat(\mathcal{S}4_{uc}, REGC)$ is in EXPTIME.

- Actually, $\mathcal{C}c$ -formulas can encode exponentially large grids.
- We take sequences of variables r_n, \dots, r_1 and s_n, \dots, s_1 , using them to encode pairs of numbers (i, j) ($0 \leq i, j, < 2^n$).
- And we use the number-coding tricks (familiar from $\mathcal{C}c$) to create a ‘chess’-board pattern



with each square corresponding to a product

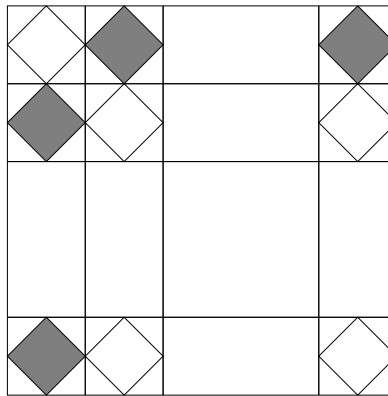
$$\pm r_n \cdot \dots \cdot \pm r_1 \cdot \pm s_n \cdot \dots \cdot \pm s_1.$$

and the grid connectivity represented by C .

- In the larger language $\mathcal{C}cc$, we can add formulas

$$c^{\leq 2^{n-1}}((r_0 \cdot s_0) + (-r_0 \cdot -s_0)) \quad c^{\leq 2^{n-1}}((r_0 \cdot -s_0) + (-r_0 \cdot s_0)).$$

- This enforces connectedness of each of the 2^{n-1} black squares and each of the 2^{n-1} white squares:



- As a result, we have:

$\mathcal{S}at(\mathcal{C}cc, \text{REGC})$ is NEXPTIME-hard.

- A matching upper bound is available:

$\mathcal{S}at(\mathcal{S}4_u cc, \text{REGC})$ is in NEXPTIME.

- We mention in passing that, in the presence of the connectedness predicate, we can drop the predicate C in the languages $\mathcal{C}c$ and $\mathcal{C}cc$.
- Thus, $\mathcal{B}c$ is defined by the signature

$$0, 1, +, \cdot, c$$

and $\mathcal{B}cc$ is defined by the signature

$$0, 1, +, \cdot, c^{\leq k}, c^{\geq k}$$

where $k \geq 0$.

- This reduces expressive power, but not complexity:

$Sat(\mathcal{B}c, \text{REGC})$ is EXPTIME-complete;

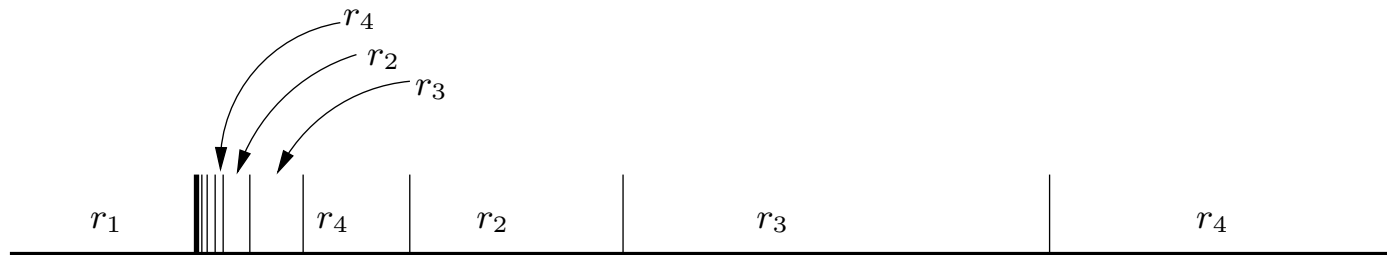
$Sat(\mathcal{B}cc, \text{REGC})$ is NEXPTIME-complete.

- Finally, we consider what happens when the languages $\mathcal{RCC}\text{-}\delta c$, \mathcal{Cc} and \mathcal{Cc} are interpreted over **low-dimensional Euclidean spaces**.
- For the spaces \mathbb{R}^n , it is natural to consider the frames
 - $(\mathbb{R}^n, \mathbf{RC}(\mathbb{R}^n))$ —the regular closed sets in \mathbb{R}^n ;
 - $(\mathbb{R}^n, \mathbf{RCS}(\mathbb{R}^n))$ —the reg. closed semi-algebraic sets in \mathbb{R}^n .
- Recall that the semi-algebraic sets count as ‘tame’:
 - They have finitely many components
 - They have the ‘curve-selection’ property

- Consider the \mathcal{RCC} -8c-formula

$$c(r_1) \wedge \bigwedge_{1 \leq i < j \leq 4} EC(r_i, r_j).$$

- This formula is satisfiable over $(\mathbb{R}, \mathbf{RC}(\mathbb{R}))$, e.g. by



But it is not satisfiable over $(\mathbb{R}, \mathbf{RCS}(\mathbb{R}))$.

- Thus, $Sat(\mathcal{RCC}\text{-}8c, (\mathbb{R}, \mathbf{RC}(\mathbb{R}))) \neq Sat(\mathcal{RCC}\text{-}8c, (\mathbb{R}, \mathbf{RCS}(\mathbb{R})))$.
- We know that: $Sat(\mathcal{RCC}\text{-}8c, (\mathbb{R}, \mathbf{RCS}(\mathbb{R})))$ is NP_{TIME}-complete; $Sat(\mathcal{RCC}\text{-}8c, (\mathbb{R}, \mathbf{RC}(\mathbb{R})))$ is NP_{TIME}-hard and in PSPACE.
- Also: $Sat(\mathcal{C}c, (\mathbb{R}, \mathbf{RC}(\mathbb{R}))) \neq Sat(\mathcal{C}c, (\mathbb{R}, \mathbf{RCS}(\mathbb{R})))$, and both these problems are PSPACE-complete.
- However: $Sat(\mathcal{B}c, (\mathbb{R}, \mathbf{RC}(\mathbb{R}))) = Sat(\mathcal{C}c, (\mathbb{R}, \mathbf{RCS}(\mathbb{R})))$, and this problem is NP_{TIME}-complete.

- In \mathbb{R}^2 , a rather different picture emerges:
- We know

$$\mathcal{Sat}(\mathcal{RCC}\text{-}8c, (\mathbb{R}, \mathbf{RC}(\mathbb{R}^2))) = \mathcal{Sat}(\mathcal{RCC}\text{-}8c, (\mathbb{R}, \mathbf{RCS}(\mathbb{R}^2))).$$
- The problem $\mathcal{Sat}(\mathcal{RCC}\text{-}8c, (\mathbb{R}, D))$, where D is the set of disc-homeomorphisms in the plane, is **NPTIME-complete** (Schaefer, Sedgwick and Štefankovič, 2003).
- It is then easy to show that $\mathcal{Sat}(\mathcal{RCC}\text{-}8c, (\mathbb{R}, \mathbf{RCS}))$ is also NPTIME-complete.
- However, we have

$$\begin{aligned} \mathcal{Sat}(\mathcal{Bc}, (\mathbb{R}, \mathbf{RC}(\mathbb{R}^2))) &\neq \mathcal{Sat}(\mathcal{Bc}, (\mathbb{R}, \mathbf{RCS}(\mathbb{R}^2))) \\ \mathcal{Sat}(\mathcal{Cc}, (\mathbb{R}, \mathbf{RC}(\mathbb{R}^2))) &\neq \mathcal{Sat}(\mathcal{Cc}, (\mathbb{R}, \mathbf{RCS}(\mathbb{R}^2))). \end{aligned}$$

The decidability of these problems is not known.

- Conceptual summary:
 - Topological languages: $\mathcal{RCC-8}$, \mathcal{B} , \mathcal{C} , $\mathcal{S4}_u$ plus c , $c^{\leq k}$, $c^{\geq k}$
 - Topological frame classes: ALL , REGC , $\{(\mathbb{R}^n, \mathbf{RCS}(\mathbb{R}^n))\}$.
- Technical summary:

	REGC	$\mathbf{RC}(\mathbb{R})$	$\mathbf{RCS}(\mathbb{R})$	$\mathbf{RC}(\mathbb{R}^2)$	$\mathbf{RCS}(\mathbb{R}^2)$
$\mathcal{RCC-8c}$	NP	$\geq \text{NP} \leq \text{PSPACE}$	NP	NP	NP
$\mathcal{RCC-8cc}$	NP	$\geq \text{NP} \leq \text{PSPACE}$	$\geq \text{NP} \leq \text{EXPTIME}$	$\geq \text{NP} \leq \text{NEXPTIME}$	$\geq \text{NP} \leq \text{NEXPTIME}$
\mathcal{Bc}	EXPTIME	NP	NP	$\geq \text{PSPACE}$	$\geq \text{PSPACE}$
\mathcal{Cc}	EXPTIME	PSPACE	PSPACE	$\geq \text{EXPTIME}$	$\geq \text{EXPTIME}$
\mathcal{Bcc}	NEXPTIME	$\geq \text{NP} \leq \text{PSPACE}$	$\geq \text{NP}$	$\geq \text{PSPACE}$	$\geq \text{PSPACE}$
\mathcal{Ccc}	NEXPTIME	PSPACE	$\geq \text{PSPACE}$	$\geq \text{NEXPTIME}$	$\geq \text{NEXPTIME}$

	ALL	\mathbb{R}	$\mathcal{S}(\mathbb{R})$	\mathbb{R}^2	$\mathcal{S}(\mathbb{R}^2)$
$\mathcal{S4}_uc$	EXPTIME	PSPACE	PSPACE	$\geq \text{EXPTIME}$	$\geq \text{EXPTIME}$
$\mathcal{S4}_ucc$	NEXPTIME	PSPACE	PSPACE	$\geq \text{NEXPTIME}$	$\geq \text{NEXPTIME}$